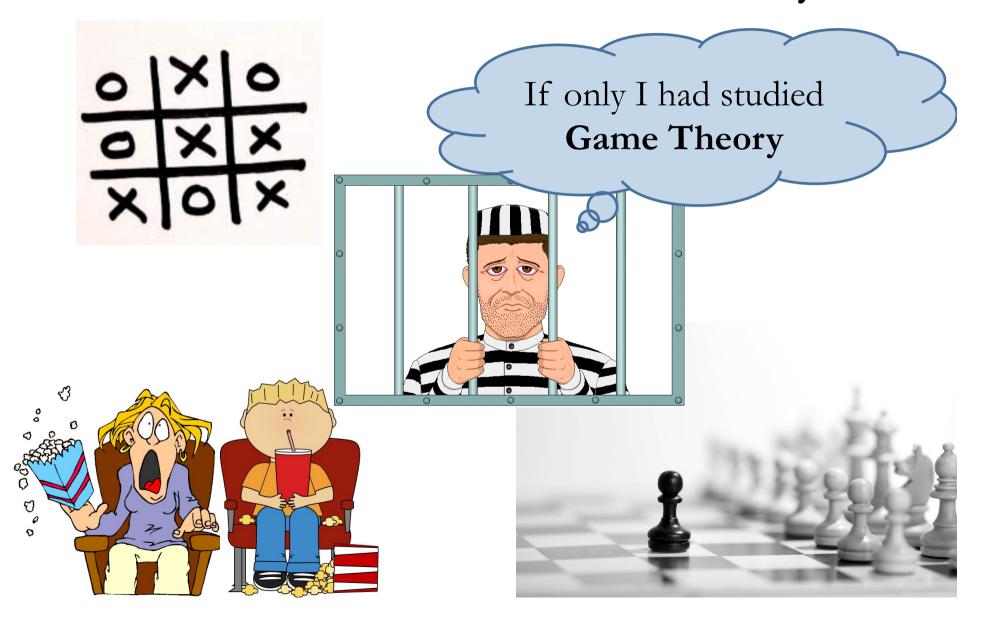
#### Introduction to Game Theory



#### Introduction to Game Theory

Game theory is the mathematical study of interaction among independent, self-interested agents.

### Outlook

#### Games in Normal Form

Perfect-information Sequential Actions Games

Imperfect-information SA Games

**Repeated Games** 

Bayesian Games

**Coalitional Games** 

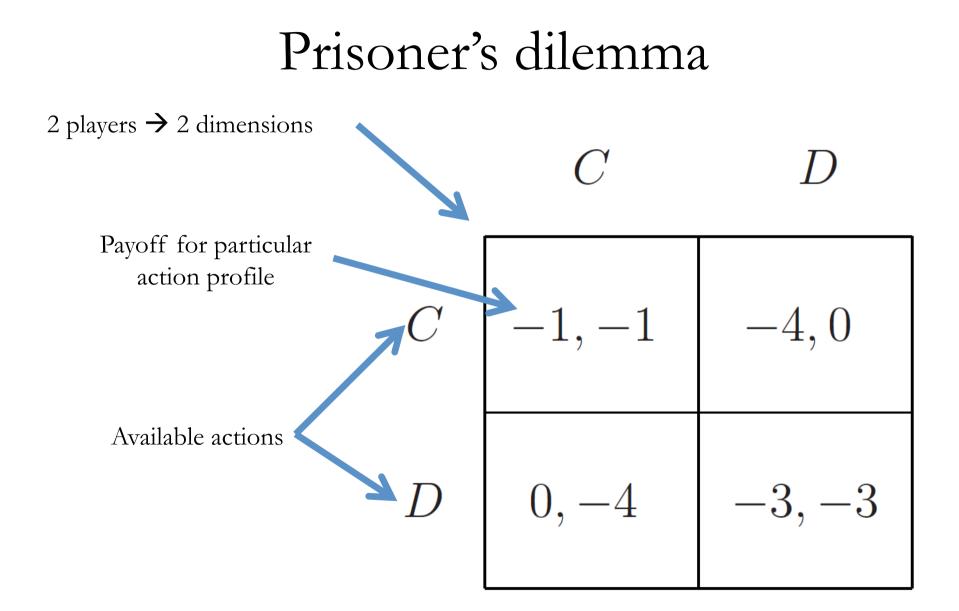
#### Normal Form

**Definition 1.2.1 (Normal-form game).** A (finite, n-person) normal-form game is a tuple (N, A, u), where:

- N is a finite set of n players, indexed by i;
- $A = A_1 \times \cdots \times A_n$ , where  $A_i$  is a finite set of actions available to player *i*. Each vector  $a = (a_1, \ldots, a_n) \in A$  is called an action profile;
- $u = (u_1, ..., u_n)$  where  $u_i : A \mapsto \mathbb{R}$  is a real-valued utility (or payoff) function for player i.

Actually, it's a table :) such as this one

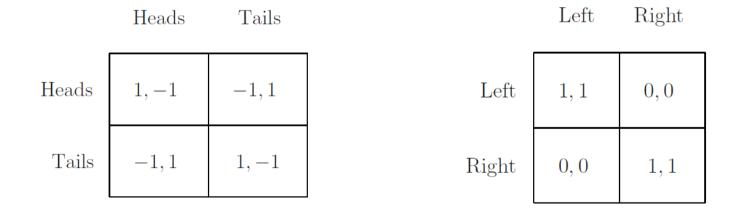
$$\begin{array}{c|c} C & -1, -1 & -4, 0 \\ \hline D & 0, -4 & -3, -3 \end{array}$$



## Special cases

**Definition 1.3.1 (Common-payoff game).** A common-payoff game is a game in which for all action profiles  $a \in A_1 \times \cdots \times A_n$  and any pair of agents i, j, it is the case that  $u_i(a) = u_j(a)$ .

**Definition 1.3.2 (Constant-sum game).** A two-player normal-form game is constant-sum if there exists a constant c such that for each strategy profile  $a \in A_1 \times A_2$  it is the case that  $u_1(a) + u_2(a) = c$ .



## Strategies

**Definition 1.4.1 (Mixed strategy).** Let (N, A, u) be a normal-form game, and for any set X let  $\Pi(X)$  be the set of all probability distributions over X. Then the set of mixed strategies for player i is  $S_i = \Pi(A_i)$ .

**Definition 1.4.2 (Mixed-strategy profile).** The set of mixed-strategy profiles is simply the Cartesian product of the individual mixed-strategy sets,  $S_1 \times \cdots \times S_n$ .

**Definition 1.4.3 (Support).** The support of a mixed strategy  $s_i$  for a player *i* is the set of pure strategies  $\{a_i | s_i(a_i) > 0\}$ .

**Definition 1.4.4 (Expected utility of a mixed strategy).** Given a normal-form game (N, A, u), the expected utility  $u_i$  for player i of the mixed-strategy profile  $s = (s_1, \ldots, s_n)$  is defined as

$$u_i(s) = \sum_{a \in \mathcal{A}} u_i(a) \prod_{j=1}^n s_j(a_j).$$

# Strategy profile dominance



How to measure "goodness" of a strategy profile?



Is strategy profile A better than B?

**Definition 2.1.1 (Pareto domination).** Strategy profile s Pareto dominates strategy profile s' if for all  $i \in N$ ,  $u_i(s) \ge u_i(s')$ , and there exists some  $j \in N$  for which  $u_j(s) > u_j(s')$ .

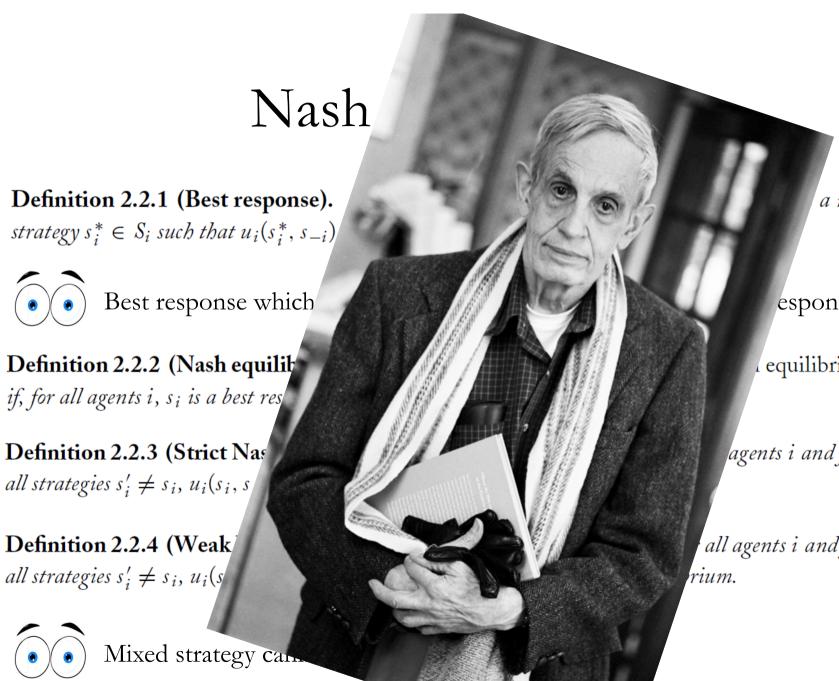
**Definition 2.1.2 (Pareto optimality).** Strategy profile s is Pareto optimal, or strictly Pareto efficient, if there does not exist another strategy profile  $s' \in S$  that Pareto dominates s.



There is always some Pareto optimal (pure) strategy profile.



In common-payoff games, all Pareto optimal strategy profiles have the same payoffs.



a mixed

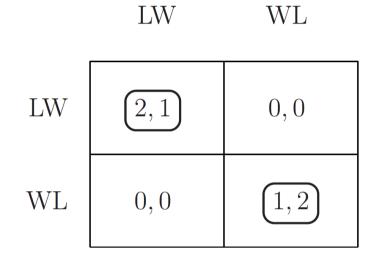
esponses.

l equilibrium

agents i and for

all agents i and for

## Nash Equilibrium example





Are these the only equilibria?



Unfortunately no...

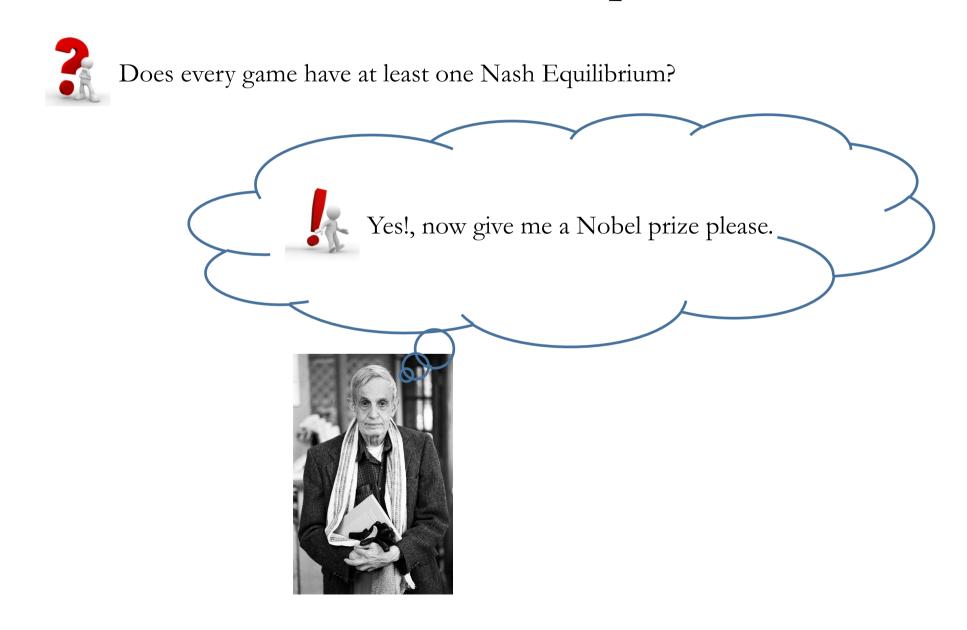
TT

$$U_{wife}(LW) = U_{wife}(WL)$$
  
2 \* p + 0 \* (1 - p) = 0 \* p + 1 \* (1 - p)  
$$p = \frac{1}{3}$$

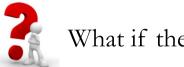
TT



## Existence of Nash Equilibrium



### MaxMin & MinMax



What if the other players really don't like me?

**Definition 3.1.1 (Maxmin).** The maxmin strategy for player *i* is  $\arg \max_{s_i} \min_{s_{-i}} u_i(s_i, s_{-i})$ , and the maxmin value for player *i* is  $\max_{s_i} \min_{s_{-i}} u_i(s_i, s_{-i})$ .

**Definition 3.1.2 (Minmax, two-player).** In a two-player game, the minmax strategy for player *i against player* -i is  $\arg\min_{s_i} \max_{s_{-i}} u_{-i}(s_i, s_{-i})$ , and player -i's minmax value is  $\min_{s_i} \max_{s_{-i}} u_{-i}(s_i, s_{-i})$ .

**Definition 3.1.3 (Minmax, n-player).** In an n-player game, the minmax strategy for player i against player  $j \neq i$  is i's component of the mixed-strategy profile  $s_{-j}$  in the expression  $\arg\min_{s_{-j}}\max_{s_j}u_j(s_j, s_{-j})$ , where -j denotes the set of players other than j. As before, the minmax value for player j is  $\min_{s_{-j}}\max_{s_j}u_j(s_j, s_{-j})$ .





#### MinMax/MaxMin and Nash

**Theorem 3.1.4 (Minimax theorem (von Neumann, 1928)).** In any finite, two-player, zerosum game, in any Nash equilibrium<sup>1</sup> each player receives a payoff that is equal to both his maxmin value and his minmax value.



## Strategy dominance

**Definition 3.3.1 (Domination).** Let  $s_i$  and  $s'_i$  be two strategies of player *i*, and  $S_{-i}$  the set of all strategy profiles of the remaining players. Then

- 1.  $s_i$  strictly dominates  $s'_i$  if for all  $s_{-i} \in S_{-i}$ , it is the case that  $u_i(s_i, s_{-i}) > u_i(s'_i, s_{-i})$ .
- 2.  $s_i$  weakly dominates  $s'_i$  if for all  $s_{-i} \in S_{-i}$ , it is the case that  $u_i(s_i, s_{-i}) \ge u_i(s'_i, s_{-i})$ , and for at least one  $s_{-i} \in S_{-i}$ , it is the case that  $u_i(s_i, s_{-i}) > u_i(s'_i, s_{-i})$ .
- 3.  $s_i$  very weakly dominates  $s'_i$  if for all  $s_{-i} \in S_{-i}$ , it is the case that  $u_i(s_i, s_{-i}) \ge u_i(s'_i, s_{-i})$ .

If one strategy dominates all others, we say that it is (strongly, weakly or very weakly) *dominant*.

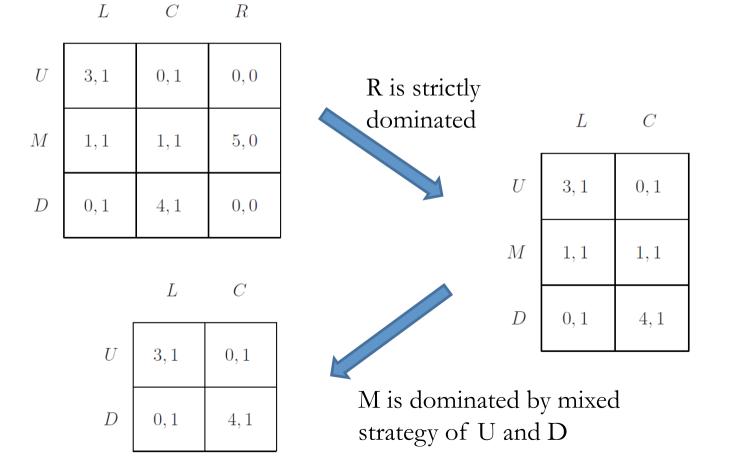
**Definition 3.3.2 (Dominant strategy).** A strategy is strictly (resp., weakly; very weakly) dominant for an agent if it strictly (weakly; very weakly) dominates any other strategy for that agent.

**Definition 3.3.3 (Dominated strategy).** A strategy  $s_i$  is strictly (weakly; very weakly) dominated for an agent i if some other strategy  $s'_i$  strictly (weakly; very weakly) dominates  $s_i$ .

# Strategy dominance



We can remove strictly dominated pure strategies as they will not be a part of any best response.



#### Outlook

Games in Normal Form

#### Perfect-information Sequential Actions Games

Imperfect-information SA Games

**Repeated Games** 

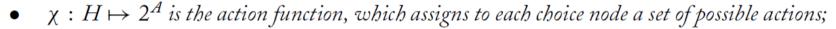
Bayesian Games

**Coalitional Games** 

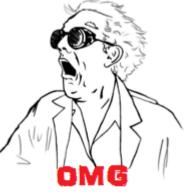
#### Perfect-information Game

**Definition 4.1.1 (Perfect-information game).** A (finite) perfect-information game (in extensive form) is a tuple  $G = (N, A, H, Z, \chi, \rho, \sigma, u)$ , where:

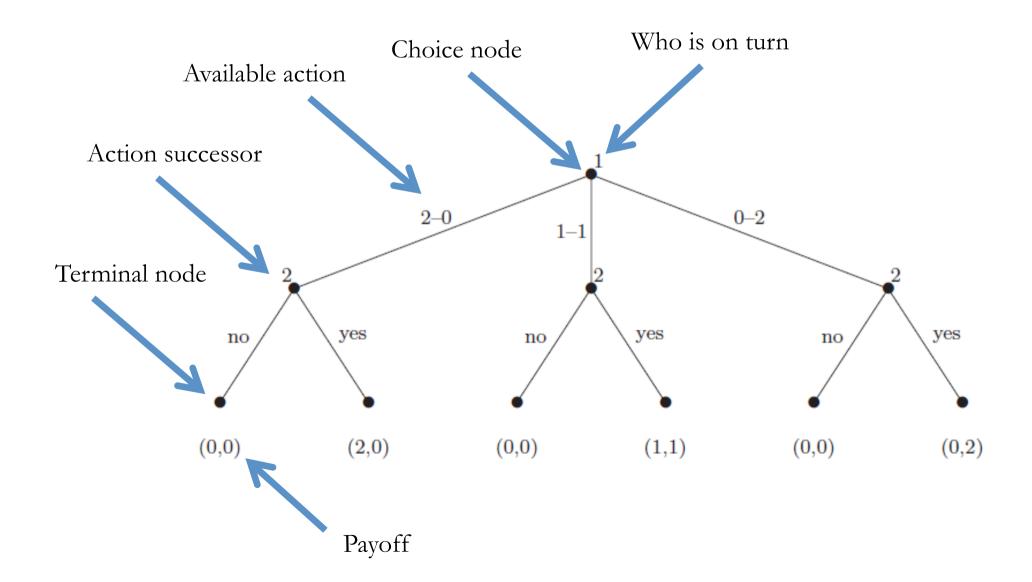
- N is a set of n players;
- A is a (single) set of actions;
- *H* is a set of nonterminal choice nodes;
- Z is a set of terminal nodes, disjoint from H;



- $\rho: H \mapsto N$  is the player function, which assigns to each nonterminal node a player  $i \in N$  who chooses an action at that node;
- $\sigma: H \times A \mapsto H \cup Z$  is the successor function, which maps a choice node and an action to a new choice node or terminal node such that for all  $h_1, h_2 \in H$  and  $a_1, a_2 \in A$ , if  $\sigma(h_1, a_1) = \sigma(h_2, a_2)$  then  $h_1 = h_2$  and  $a_1 = a_2$ ; and
- $u = (u_1, \ldots, u_n)$ , where  $u_i : Z \mapsto \mathbb{R}$  is a real-valued utility function for player i on the terminal nodes Z.



#### Perfect-information Game



#### Perfect-information Game

**Definition 4.1.1 (Perfect-information game).** A (finite) perfect-information game (in extensive form) is a tuple  $G = (N, A, H, Z, \chi, \rho, \sigma, u)$ , where:

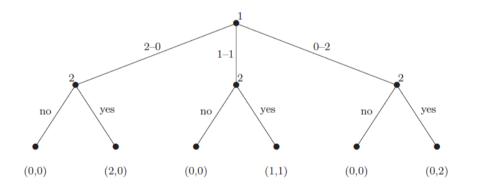
- N is a set of n players;
- A is a (single) set of actions;
- *H* is a set of nonterminal choice nodes;
- Z is a set of terminal nodes, disjoint from H;
- $\chi: H \mapsto 2^A$  is the action function, which assigns to each choice node a set of possible actions;
- $\rho: H \mapsto N$  is the player function, which assigns to each nonterminal node a player  $i \in N$  who chooses an action at that node;
- $\sigma: H \times A \mapsto H \cup Z$  is the successor function, which maps a choice node and an action to a new choice node or terminal node such that for all  $h_1, h_2 \in H$  and  $a_1, a_2 \in A$ , if  $\sigma(h_1, a_1) = \sigma(h_2, a_2)$  then  $h_1 = h_2$  and  $a_1 = a_2$ ; and
- $u = (u_1, \ldots, u_n)$ , where  $u_i : Z \mapsto \mathbb{R}$  is a real-valued utility function for player i on the terminal nodes Z.



## Strategies

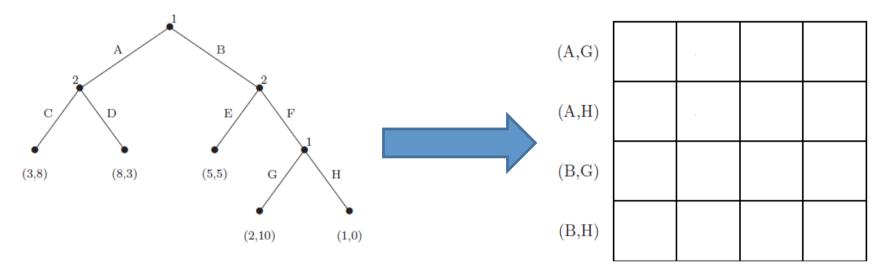
**Definition 4.2.1 (Pure strategies).** Let  $G = (N, A, H, Z, \chi, \rho, \sigma, u)$  be a perfect-information extensive-form game. Then the pure strategies of player i consist of the Cartesian product  $\prod_{b \in H, \rho(b)=i} \chi(b)$ .

Strategy must define actions even in the unused branches.



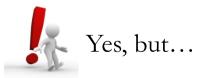
 $S_{1} = \{2-0, 1-1, 0-2\}$  $S_{2} = \{(yes, yes, yes), (yes, yes, no), (yes, no, yes), (yes, no, no), (no, yes, yes), (no, yes, no), (no, no, yes), (no, no, no)\}$ 

## Normal Games vs. PI Games





So this can be done for every Perfect-information Game?



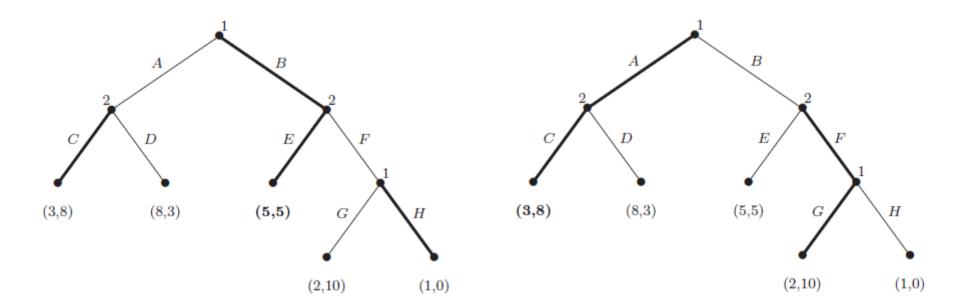


And what about the reverse?

No! Consider the Prisoner's dilemma.

### PI Games Equilibrium

**Theorem 4.2.2.** Every (finite) perfect-information game in extensive form has a pure-strategy Nash equilibrium.



In the  $1^{nd}$  (left) equilibrium, player 1 plays H only as a **threat**.

## Perfect-information Subgames

**Definition 4.3.1 (Subgame).** Given a perfect-information extensive-form game G, the subgame of G rooted at node h is the restriction of G to the descendants of h. The set of subgames of G consists of all of subgames of G rooted at some node in G.

**Definition 4.3.2 (Subgame-perfect equilibrium).** The subgame-perfect equilibria (SPE) of a game G are all strategy profiles s such that for any subgame G' of G, the restriction of s to G' is a Nash equilibrium of G'.



Subgame-perfect equilibrium is also a Nash equilibrium.



The "problematic" equilibrium is not subgame-perfect.

## Backward Induction



```
function BACKWARDINDUCTION (node b) returns u(b)

if h \in Z then

\lfloor return u(h)

best\_util \leftarrow -\infty

forall a \in \chi(h) do

\lfloor util\_at\_child \leftarrow BACKWARDINDUCTION(\sigma(h, a))

if util\_at\_child_{\rho(h)} > best\_util_{\rho(h)} then

\lfloor best\_util \leftarrow util\_at\_child

return best\_util
```

// h is a terminal node



It is actually minimax algorithm for two-player, zero-sum games.

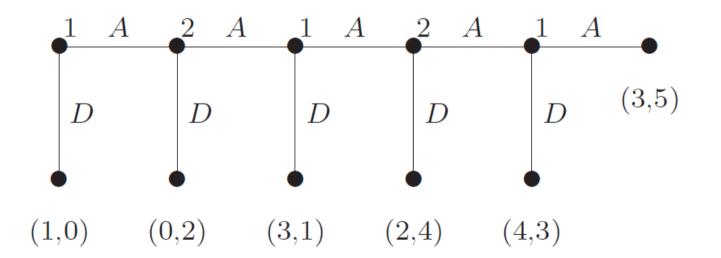
### Backward Induction



We have an efficient algorithm... any drawbacks?



Well, games can be big... e.g., chess game will have approx 10 ^150 nodes.



### Outlook

Games in Normal Form

Perfect-information Sequential Actions Games

#### Imperfect-information SA Games

**Repeated Games** 

Bayesian Games

**Coalitional Games** 

## Imperfect-information Games

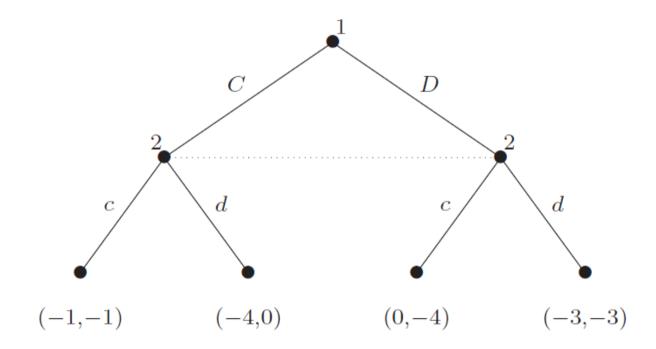
**Definition 5.1.1 (Imperfect-information game).** An imperfect-information game (in extensive form) is a tuple  $(N, A, H, Z, \chi, \rho, \sigma, u, I)$ , where:

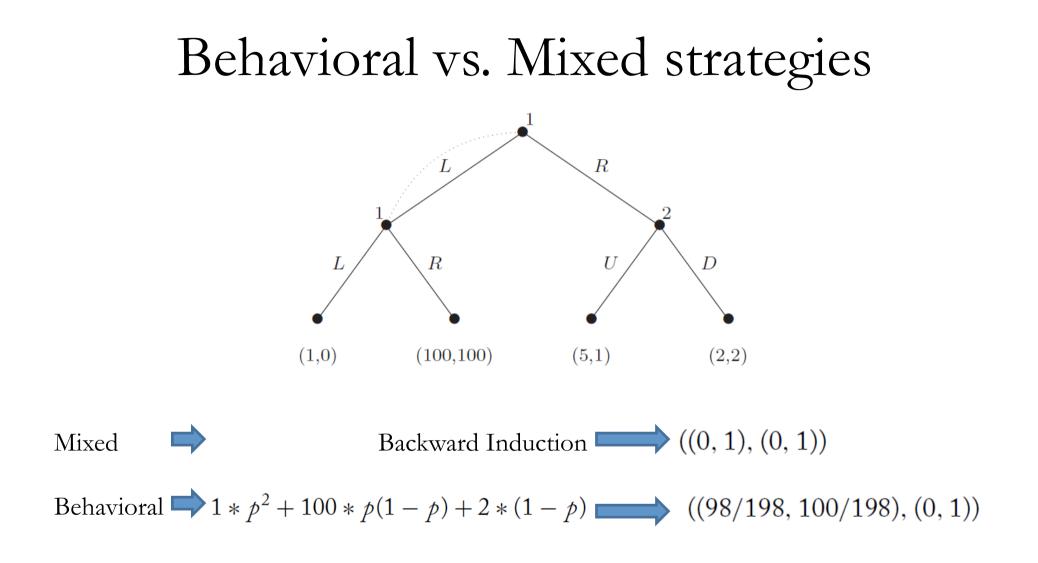
- $(N, A, H, Z, \chi, \rho, \sigma, u)$  is a perfect-information extensive-form game; and
- I = (I<sub>1</sub>,..., I<sub>n</sub>), where I<sub>i</sub> = (I<sub>i,1</sub>,..., I<sub>i,k<sub>i</sub></sub>) is an equivalence relation on (i.e., a partition of) {h ∈ H : ρ(h) = i} with the property that χ(h) = χ(h') and ρ(h) = ρ(h') whenever there exists a j for which h ∈ I<sub>i,j</sub> and h' ∈ I<sub>i,j</sub>.

**Definition 5.2.1 (Pure strategies).** Let  $G = (N, A, H, Z, \chi, \rho, \sigma, u, I)$  be an imperfectinformation extensive-form game. Then the pure strategies of player *i* consist of the Cartesian product  $\prod_{I_{i,j} \in I_i} \chi(I_{i,j})$ .

## Imperfect-information Games

) Prisoner's dilemma can be represented in the imperfect-information form.





Behavioral and Mixed equilibrium sets might be not comparable

#### Outlook

Games in Normal Form

Perfect-information Sequential Actions Games

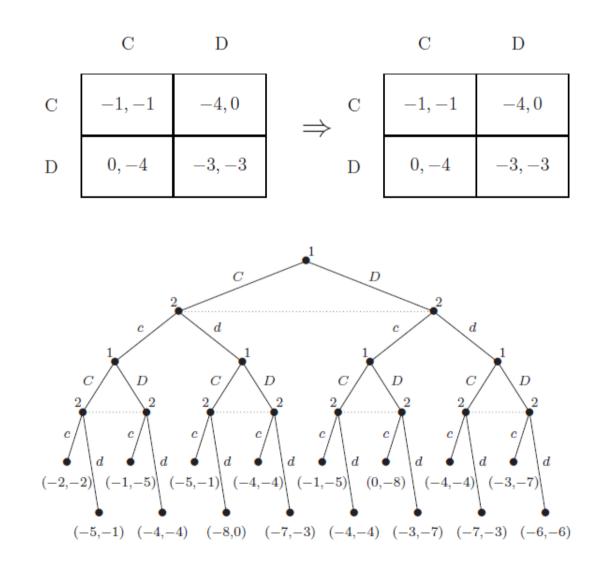
Imperfect-information SA Games

➢ Repeated Games

Bayesian Games

**Coalitional Games** 

### Finitely repeated Games



# Infinitely repeated Games

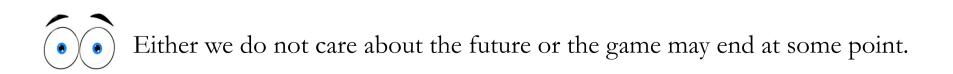


What is the proper definition of the payoffs in IR Games?

**Definition 6.2.1 (Average reward).** Given an infinite sequence of payoffs  $r_i^{(1)}$ ,  $r_i^{(2)}$ , ... for player *i*, the average reward of *i* is

$$\lim_{k \to \infty} \frac{\sum_{j=1}^k r_i^{(j)}}{k}.$$

**Definition 6.2.2 (Discounted reward).** Given an infinite sequence of payoffs  $r_i^{(1)}, r_i^{(2)}, \ldots$  for player *i*, and a discount factor  $\beta$  with  $0 \le \beta \le 1$ , the future discounted reward of *i* is  $\sum_{j=1}^{\infty} \beta^j r_i^{(j)}$ .



#### Folk theorem



So what about the Nash Equilibria in IR Games?

Let us define:  $v_i = \min_{s_{-i} \in S_{-i}} \max_{s_i \in S_i} u_i(s_{-i}, s_i)$ 

**Definition 6.2.3 (Enforceable).** A payoff profile  $r = (r_1, r_2, ..., r_n)$  is enforceable if  $\forall i \in N$ ,  $r_i \geq v_i$ .

**Definition 6.2.4 (Feasible).** A payoff profile  $r = (r_1, r_2, ..., r_n)$  is feasible if there exist rational, nonnegative values  $\alpha_a$  such that for all i, we can express  $r_i$  as  $\sum_{a \in A} \alpha_a u_i(a)$ , with  $\sum_{a \in A} \alpha_a = 1$ .

In other words, a payoff profile is feasible if it is a convex, rational combination of the outcomes in G.

**Theorem 6.2.5 (Folk Theorem).** Consider any *n*-player normal-form game G and any payoff profile  $r = (r_1, r_2, ..., r_n)$ .

- 1. If r is the payoff profile for any Nash equilibrium s of the infinitely repeated G with average rewards, then for each player i,  $r_i$  is enforceable.
- 2. If r is both feasible and enforceable, then r is the payoff profile for some Nash equilibrium of the infinitely repeated G with average rewards.

### Outlook

Games in Normal Form

Perfect-information Sequential Actions Games

Imperfect-information SA Games

Repeated Games

> Bayesian Games

**Coalitional Games** 

## Even more uncertainty



We know what to do when we are uncertain about the history; however, what about if we are not sure about the available actions or even which game we are playing?



We can reduce these uncertainties to uncertain payoffs.

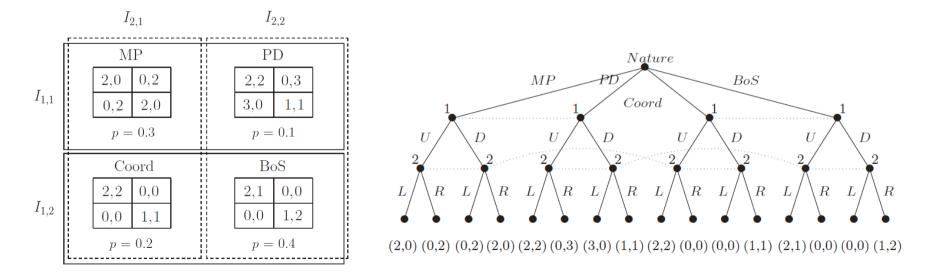
	L	R		L	С	R
U	1, 1	1, 3	U	1, 1	0, 2	1,3
D	0, 5	1, 13	D	0, 5	2, 8	1, 13

U	1, 1	0, -100	1, 3
D	0, 5	2, -100	1,13

## Bayesian Games I

**Definition 7.1.1 (Bayesian game: information sets).** A Bayesian game *is a tuple* (N, G, P, I) *where:* 

- N is a set of agents;
- G is a set of games with N agents each such that if  $g, g' \in G$  then for each agent  $i \in N$  the strategy space in g is identical to the strategy space in g';
- $P \in \Pi(G)$  is a common prior over games, where  $\Pi(G)$  is the set of all probability distributions over G; and
- $I = (I_1, ..., I_N)$  is a tuple of partitions of G, one for each agent.



#### Bayesian Games II

**Definition 7.1.2 (Bayesian game: types).** A Bayesian game is a tuple  $(N, A, \Theta, p, u)$  where:

- N is a set of agents;
- $A = A_1 \times \cdots \times A_n$ , where  $A_i$  is the set of actions available to player *i*;
- $\Theta = \Theta_1 \times \ldots \times \Theta_n$ , where  $\Theta_i$  is the type space of player *i*;
- $p: \Theta \mapsto [0, 1]$  is a common prior over types; and
- $u = (u_1, \ldots, u_n)$ , where  $u_i : A \times \Theta \mapsto \mathbb{R}$  is the utility function for player *i*.

Agent knows his own type while does not know types of the others.

#### ISBG to TBG

		$I_{2,1}$		$I_{2,2}$			
<i>I</i> <sub>1,1</sub>			,2 2,0 3	$ \begin{array}{c c} PD \\ \hline 2,2 & 0,3 \\ \hline 3,0 & 1,1 \\ p = 0.1 \end{array} $			
<i>I</i> <sub>1,2</sub>		$ \begin{array}{c cccc} Coord \\ \hline 2,2 & 0,0 \\ \hline 0,0 & 1,1 \\ \hline p = 0.2 \end{array} $			BoS     2,1 0,0     0,0 1,2 $p = 0.4 $		
-	$a_1$	$a_2$	$\theta_1$	$\theta_{2}$	$u_1$	$u_2$	
-	а <b>1</b> U	а <b>2</b> L			$u_1$	$u_2$	
-			$\theta_{1,1}$	$\begin{array}{c} \theta_2 \\ \\ \theta_{2,1} \\ \\ \theta_{2,2} \end{array}$			
-	U	L		$\theta_{2,1}$	2	0	
-	U U	L L	$\begin{array}{c} \theta_{1,1} \\ \theta_{1,1} \end{array}$	$\begin{array}{c} \theta_{2,1} \\ \theta_{2,2} \end{array}$	$\frac{2}{2}$	$\begin{array}{c} 0 \\ 2 \end{array}$	
-	U U U	L L L	$\begin{array}{c} \theta_{1,1} \\ \theta_{1,1} \\ \theta_{1,2} \end{array}$	$\begin{array}{c} \theta_{2,1} \\ \theta_{2,2} \\ \theta_{2,1} \end{array}$	2 2 2	$\begin{array}{c} 0 \\ 2 \\ 2 \end{array}$	
-	U U U U	L L L L	$\begin{array}{c} \theta_{1,1} \\ \theta_{1,1} \\ \theta_{1,2} \\ \theta_{1,2} \end{array}$	$\begin{array}{c} \theta_{2,1} \\ \theta_{2,2} \\ \theta_{2,1} \\ \theta_{2,2} \end{array}$	2 2 2 2	0 2 2 1	
-	U U U U U	L L L R	$\begin{array}{c} \theta_{1,1} \\ \theta_{1,1} \\ \theta_{1,2} \\ \theta_{1,2} \\ \theta_{1,1} \end{array}$	$\begin{array}{c} \theta_{2,1} \\ \theta_{2,2} \\ \theta_{2,1} \\ \theta_{2,2} \\ \theta_{2,2} \\ \theta_{2,1} \end{array}$	2 2 2 2 0	0 2 2 1 2	

 $p(\theta_{1,1}, \theta_{2,1}) = .3$   $p(\theta_{1,1}, \theta_{2,2}) = .1$   $p(\theta_{1,2}, \theta_{2,1}) = .2$   $p(\theta_{1,2}, \theta_{2,2}) = .4$ 

$a_1$	$a_2$	$ heta_1$	$\theta_{2}$	$u_1$	$u_2$
D	L	$\theta_{1,1}$	$\theta_{2,1}$	0	2
D	L	$\theta_{1,1}$	$\theta_{2,2}$	3	0
D	L	$\theta_{1,2}$	$\theta_{2,1}$	0	0
D	L	$\theta_{1,2}$	$\theta_{2,2}$	0	0
D	R	$\theta_{1,1}$	$\theta_{2,1}$	2	0
D	R	$\theta_{1,1}$	$\theta_{2,2}$	1	1
D	R	$\theta_{1,2}$	$\theta_{2,1}$	1	1
D	R	$\theta_{1,2}$	$\theta_{2,2}$	1	2

#### Expected Utility in BG

**Definition 7.2.1 (Expost expected utility).** Agent i's expost expected utility in a Bayesian game  $(N, A, \Theta, p, u)$ , where the agents' strategies are given by s and the agent' types are given by  $\theta$ , is defined as

$$EU_i(s,\theta) = \sum_{a \in \mathcal{A}} \left( \prod_{j \in N} s_j(a_j | \theta_j) \right) u_i(a,\theta).$$
(7.1)

**Definition 7.2.2 (Ex interim expected utility).** Agent i's ex interim expected utility in a Bayesian game  $(N, A, \Theta, p, u)$ , where i's type is  $\theta_i$  and where the agents' strategies are given by the mixed-strategy profile s, is defined as

$$EU_i(s, \theta_i) = \sum_{\theta_{-i} \in \Theta_{-i}} p(\theta_{-i}|\theta_i) EU_i(s, (\theta_i, \theta_{-i})).$$
(7.3)

**Definition 7.2.3 (Ex ante expected utility).** Agent i's ex ante expected utility in a Bayesian game  $(N, A, \Theta, p, u)$ , where the agents' strategies are given by the mixed-strategy profile s, is defined as

$$EU_i(s) = \sum_{\theta \in \Theta} p(\theta) EU_i(s, \theta)$$
(7.5)

#### Towards Equilibrium in BG

**Definition 7.2.4 (Best response in a Bayesian game).** The set of agent i's best responses to mixed-strategy profile  $s_{-i}$  are given by

$$BR_{i}(s_{-i}) = \arg\max_{s_{i}' \in S_{i}} EU_{i}(s_{i}', s_{-i}).$$
(7.7)

**Definition 7.2.5 (Bayes–Nash equilibrium).** A Bayes–Nash equilibrium *is a mixed-strategy* profile s that satisfies  $\forall i \ s_i \in BR_i(s_{-i})$ .

## Towards Equilibrium in BG



We can reduce BG to NG with ex ante expected utility.

$$u_{2}(UU, LL) = \sum_{\theta \in \Theta} p(\theta)u_{2}(U, L, \theta)$$
  
=  $p(\theta_{1,1}, \theta_{2,1})u_{2}(U, L, \theta_{1,1}, \theta_{2,1}) + p(\theta_{1,1}, \theta_{2,2})u_{2}(U, L, \theta_{1,1}, \theta_{2,2})$   
+  $p(\theta_{1,2}, \theta_{2,1})u_{2}(U, L, \theta_{1,2}, \theta_{2,1}) + p(\theta_{1,2}, \theta_{2,2})u_{2}(U, L, \theta_{1,2}, \theta_{2,2})$   
=  $0.3(0) + 0.1(2) + 0.2(2) + 0.4(1) = 1.$ 

#### LL LR RL RR

LL LR RL RR

UU	2, 1	1,  0.7	1, 1.2	0, 0.9	<i>ex interim</i> after observing	UU	2, 0.5	1.5,  0.75	0.5, 2	0, 2.25
UD	0.8, 0.2	1, 1.1	0.4, 1	0.6, 1.9	0	UD	2, 0.5	1.5,  0.75	0.5, 2	0, 2.25
DU	1.5, 1.4	0.5, 1.1	1.7, 0.4	0.7, 0.1		DU	0.75,  1.5	0.25, 1.75	2.25, 0	1.75, 0.25
DD	0.3, 0.6	0.5, 1.5	1.1, 0.2	1.3, 1.1		DD	0.75, 1.5	0.25, 1.75	2.25, 0	1.75, 0.25

# Towards Equilibrium in BG



Is a Nash Equilibrium in *ex-interim* induced game meaningfull?



No! The other agents can not observe the player's type.



Now, Nash Equilibria in *ex-ante* induced game correspond to the Bayes-Nash Equilibria; thus, there is always at least one Bayes-Nash Equilibrium.



Beware! There are alternative algorithms for finding BN Eq. (e.g. expectimax).

#### Outlook

Games in Normal Form

Perfect-information Sequential Actions Games

Imperfect-information SA Games

**Repeated Games** 

Bayesian Games

Coalitional Games

## Coalitional Games

**Definition 8.1.1 (Coalitional game with transferable utility).** A coalitional game with transferable utility is a pair (N, v), where

- N is a finite<sup>2</sup> set of players, indexed by i; and
- $v: 2^N \mapsto \mathbb{R}$  associates with each coalition  $S \subseteq N$  a real-valued payoff v(S) that the coalition's members can distribute among themselves. The function v is also called the



Which coalition will form?



How should that coalition divide its payoff among its members?

**Example 8.1.2 (Voting game).** A parliament is made up of four political parties, A, B, C, and D, which have 45, 25, 15, and 15 representatives, respectively. They are to vote on whether to pass a \$100 million spending bill and how much of this amount should be controlled by each of the parties. A majority vote, that is, a minimum of 51 votes, is required in order to pass any legislation, and if the bill does not pass then every party gets zero to spend.

## Game Types

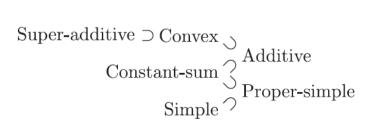
**Definition 8.2.1 (Superadditive game).** A game G = (N, v) is superadditive if for all  $S, T \subset N$ , if  $S \cap T = \emptyset$ , then  $v(S \cup T) \ge v(S) + v(T)$ .

**Definition 8.2.2 (Additive game).** A game G = (N, v) is additive (or inessential) if for all  $S, T \subset N$ , if  $S \cap T = \emptyset$ , then  $v(S \cup T) = v(S) + v(T)$ .

**Definition 8.2.4 (Convex game).** A game G = (N, v) is convex if for all  $S, T \subset N, v(S \cup T) \ge v(S) + v(T) - v(S \cap T)$ .

**Definition 8.2.5 (Simple game).** A game G = (N, v) is simple if for all  $S \subset N$ ,  $v(S) \in \{0, 1\}$ .

**Definition 8.2.3 (Constant-sum game).** A game G = (N, v) is constant sum if for all  $S \subset N$ ,  $v(S) + v(N \setminus S) = v(N)$ .



#### Some extra definitions

**Definition 8.3.1 (Feasible payoff).** Given a coalitional game (N, v), the feasible payoff set is defined as  $\{x \in \mathbb{R}^N \mid \sum_{i \in N} x_i \leq v(N)\}$ .

**Definition 8.3.2 (Pre-imputation).** Given a coalitional game (N, v), the pre-imputation set, denoted  $\mathbb{P}$ , is defined as  $\{x \in \mathbb{R}^N \mid \sum_{i \in N} x_i = v(N)\}$ .

**Definition 8.3.3 (Imputation).** Given a coalitional game (N, v), the imputation set,  $\mathcal{C}$ , is defined as  $\{x \in \mathcal{P} \mid \forall i \in N, x_i \geq v(i)\}$ .

## How to divide payoffs?



How to define "fair" division?

**Axiom 8.3.4 (Symmetry).** For any v, if i and j are interchangeable then  $\psi_i(N, v) = \psi_j(N, v)$ .

Axiom 8.3.5 (Dummy player). For any v, if i is a dummy player then  $\psi_i(N, v) = v(\{i\})$ .

**Axiom 8.3.6 (Additivity).** For any two  $v_1$  and  $v_2$ , we have for any player i that  $\psi_i(N, v_1 + v_2) = \psi_i(N, v_1) + \psi_i(N, v_2)$ , where the game  $(N, v_1 + v_2)$  is defined by  $(v_1 + v_2)(S) = v_1(S) + v_2(S)$  for every coalition S.

**Theorem 8.3.7.** Given a coalitional game (N, v), there is a unique pre-imputation  $\phi(N, v) = \phi(N, v)$  that satisfies the Symmetry, Dummy player, Additivity axioms.

#### Shapley value

**Definition 8.3.8 (Shapley value).** Given a coalitional game (N, v), the Shapley value of player *i* is given by

$$\phi_i(N, v) = \frac{1}{N!} \sum_{S \subseteq N \setminus \{i\}} |S|! (|N| - |S| - 1)! \Big[ v(S \cup \{i\}) - v(S) \Big].$$

**Example 8.1.2 (Voting game).** A parliament is made up of four political parties, A, B, C, and D, which have 45, 25, 15, and 15 representatives, respectively. They are to vote on whether to pass a \$100 million spending bill and how much of this amount should be controlled by each of the parties. A majority vote, that is, a minimum of 51 votes, is required in order to pass any legislation, and if the bill does not pass then every party gets zero to spend.

$$\phi_{A} = (3)\frac{(4-1)!(2-1)!}{4!}(100-0) + (3)\frac{(4-3)!(3-1)!}{4!}(100-0) \quad \phi_{B} = \frac{(4-2)!(2-1)!}{4!}(100-0) + \frac{(4-3)!(3-1)!}{4!}(100-0) + \frac{(4-3)!(3-1)!}{4!}(100-0) + \frac{(4-3)!(3-1)!}{4!}(100-0) = \frac{2}{24}(100) + \frac{2}{24}(100-0) = \frac{2}{24}(100) + \frac{2}{24}(100-0) = 8.33 + 8.33 = \$16.66 \text{ million.}$$

$$= 25 + 25 = \$50 \text{ million.}$$

#### Core

**Definition 8.3.9 (Core).** A payoff vector x is in the core of a coalitional game (N, v) if and only if

$$\forall S \subseteq N, \ \sum_{i \in S} x_i \ge v(S).$$



Is core always nonempty or unique?



**Theorem 8.3.10.** Every constant-sum game that is not additive has an empty core.

We say that a player *i* is a veto player if  $v(N \setminus \{i\}) = 0$ .

**Theorem 8.3.11.** In a simple game the core is empty iff there is no veto player. If there are veto players, the core consists of all payoff vectors in which the nonveto players get zero.

**Theorem 8.3.12.** *Every convex game has a nonempty core.* 

**Theorem 8.3.13.** In every convex game, the Shapley value is in the core.

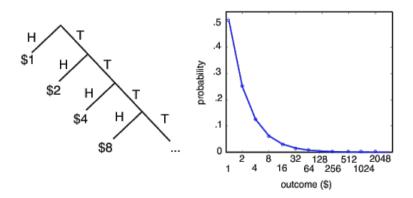
### That was theory, what about reality?



Split or Steal?







#### Thank you for your attention

